

Today 7.2, 7.3, 7.4

L23



Today 7.2, 7.3, 7.4

L23

Elastic  
potential  
energy

Today 7.2, 7.3, 7.4

L23

Conservative  
&  
Nonconservative  
Forces

Today 7.2, 7.3, 7.4

L23

Force &  
potential  
energy

Today 7.2, 7.3, 7.4

Wednesday 8.1

L23



Today 7.2, 7.3, 7.4

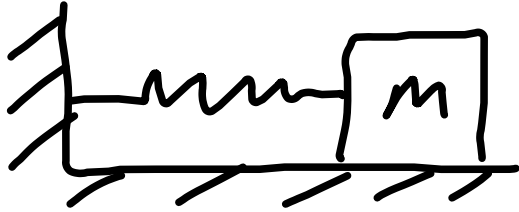
L23

Wednesday 8.1

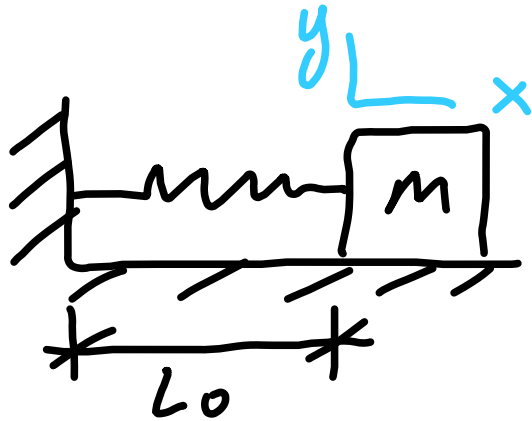
Momentum  
&  
impulse

We are going to look a bit closer at a spring system

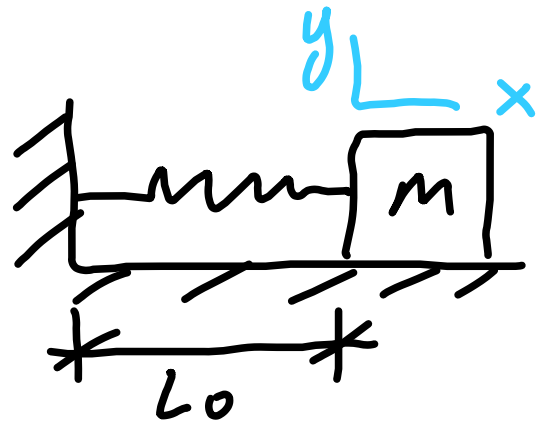
We are going to look a bit closer at a spring system



We are going to look a bit closer at a spring system

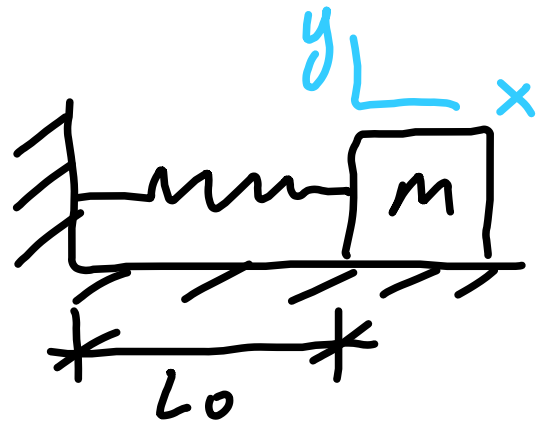


We are going to look a bit closer at a spring system



$$\vec{F}_{S \rightarrow B} = -kx \hat{i} \quad \text{Force on block}$$

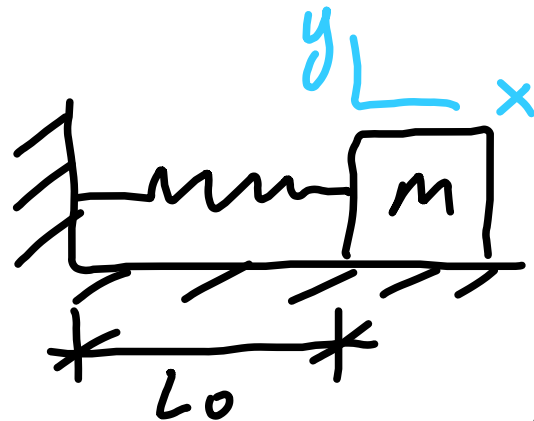
We are going to look a bit closer at a spring system



$$\vec{F}_{S \rightarrow B} = -kx \hat{i} \quad \text{Force on block}$$

$$\text{so } \vec{F}_{B \rightarrow S} = +kx \hat{i} \quad \text{Force on spring}$$

We are going to look a bit closer at a spring system

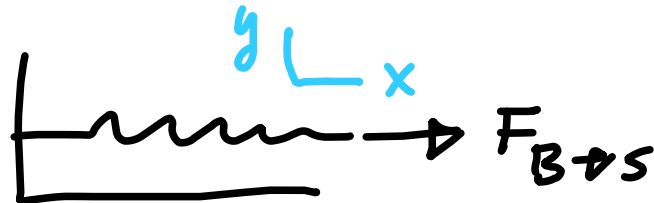


$$\vec{F}_{S \rightarrow B} = -kx \hat{i} \quad \text{Force on block}$$

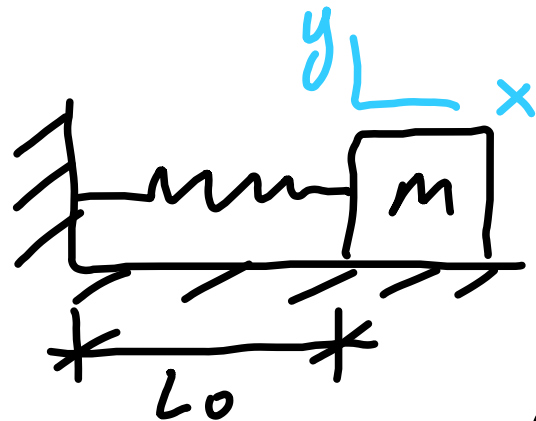
$$\text{so } \vec{F}_{B \rightarrow S} = +kx \hat{i} \quad \text{Force on Spring}$$

Look at spring wall

system



We are going to look a bit closer at a spring system

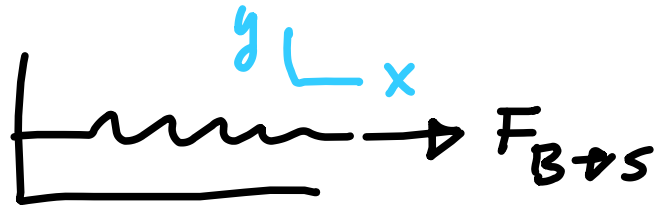


$$\vec{F}_{S \rightarrow B} = -kx \hat{i} \quad \text{Force on block}$$

so  $\vec{F}_{B \rightarrow S} = +kx \hat{i} \quad \text{Force on spring}$

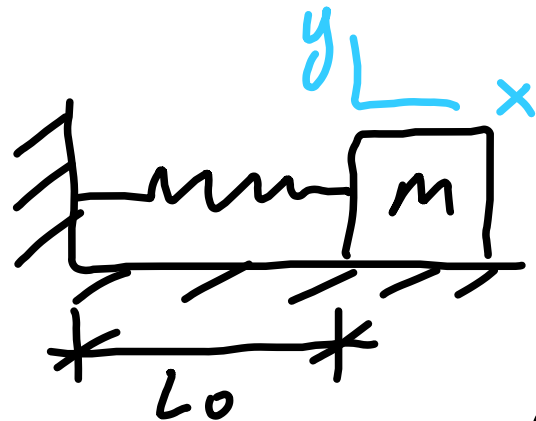
Look at spring wall

system



$$W_s = \int F dx = \frac{1}{2} kx^2$$

We are going to look a bit closer at a spring system

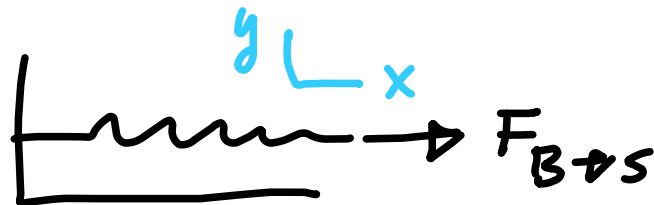


$$\vec{F}_{S \rightarrow B} = -kx \hat{i} \quad \text{Force on block}$$

so  $\vec{F}_{B \rightarrow S} = +kx \hat{i} \quad \text{Force on spring}$

Look at spring wall

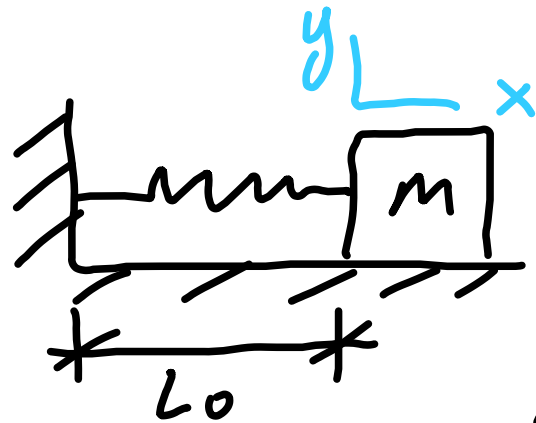
system



$$W_s = \int F dx = \frac{1}{2} kx^2$$

& since  $W = \Delta K$

We are going to look a bit closer at a spring system



$$\vec{F}_{S \rightarrow B} = -kx \hat{i} \quad \text{Force on block}$$

so  $\vec{F}_{B \rightarrow S} = +kx \hat{i} \quad \text{Force on spring}$

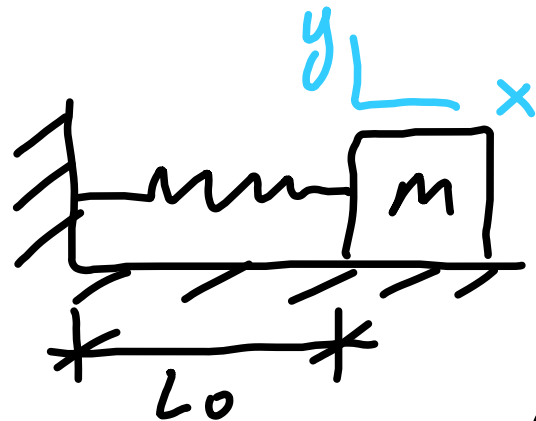
Look at spring wall

system

$$W_s = \int F dx = \frac{1}{2} kx^2$$

& since  $W = \Delta K$ , then we need to determine  $\Delta K$

We are going to look a bit closer at a spring system

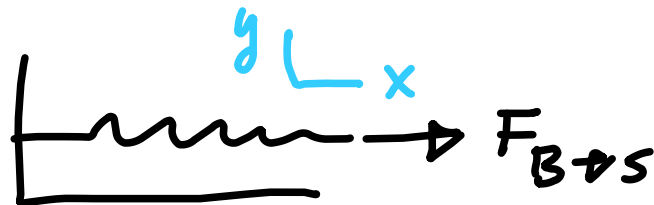


$$\vec{F}_{S \rightarrow B} = -kx \hat{i} \quad \text{Force on block}$$

$$\text{so } \vec{F}_{B \rightarrow S} = +kx \hat{i} \quad \text{Force on spring}$$

Look at spring wall system

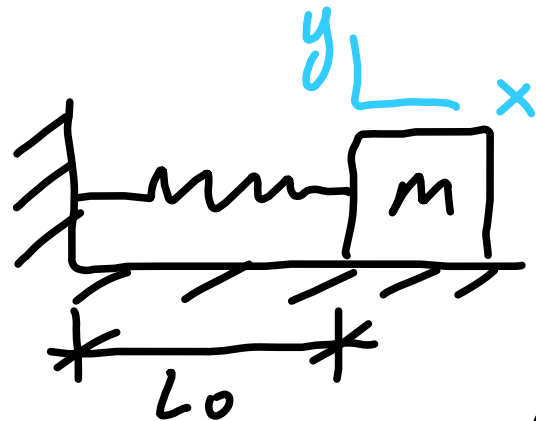
system



$$W_s = \int F dx = \frac{1}{2} kx^2$$

& since  $W = \Delta K$ , then we need to determine  $\Delta K$ . The spring has negligible mass [ideal spring]

We are going to look a bit closer at a spring system



$$\vec{F}_{S \rightarrow B} = -kx \hat{i} \quad \text{Force on block}$$

$$\text{so } \vec{F}_{B \rightarrow S} = +kx \hat{i} \quad \text{Force on spring}$$

Look at spring wall

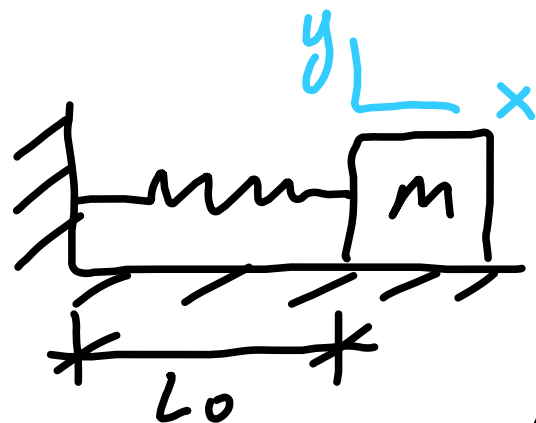
system



$$W_s = \int F dx = \frac{1}{2} kx^2$$

& since  $W = \Delta K$ , then we need to determine  $\Delta K$ . The spring has negligible mass [ideal spring] so  $\Delta K$  must refer to wall!

We are going to look a bit closer at a spring system



$$\vec{F}_{S \rightarrow B} = -kx \hat{i} \quad \text{Force on block}$$

so  $\vec{F}_{B \rightarrow S} = +kx \hat{i} \quad \text{Force on spring}$

Look at spring wall system

system

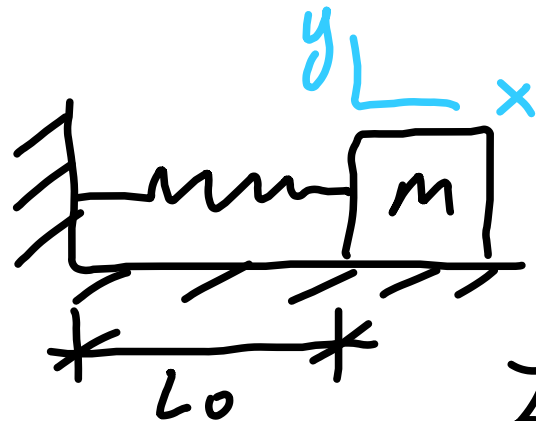


$$W_s = \int F dx = \frac{1}{2} kx^2$$

& since  $W = \Delta K$ , then we need to determine  $\Delta K$ . The spring has negligible mass [ideal spring] so  $\Delta K$

must refer to wall! NOT useful

We are going to look a bit closer at a spring system



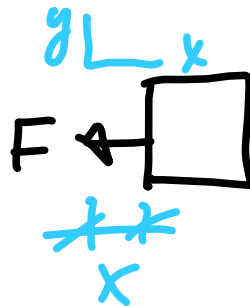
$$\vec{F}_{S \rightarrow B} = -kx \hat{i}$$

Force on block

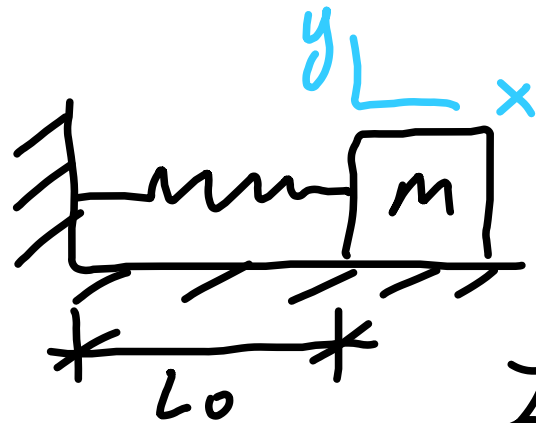
so  $\vec{F}_{B \rightarrow S} = +kx \hat{i}$

Force on spring

Look at block



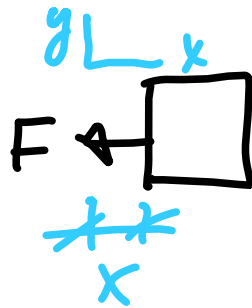
We are going to look a bit closer at a spring system



$$\vec{F}_{S \rightarrow B} = -kx \hat{i} \quad \text{Force on block}$$

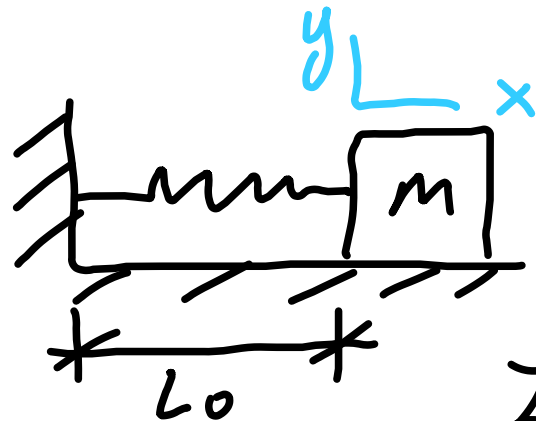
$$\text{so } \vec{F}_{B \rightarrow S} = +kx \hat{i} \quad \text{Force on spring}$$

Look at block



$$w_B = -\int kx dx$$

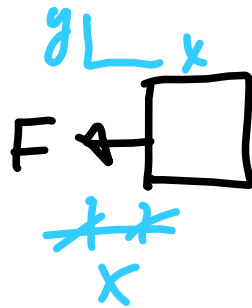
We are going to look a bit closer at a spring system



$$\vec{F}_{S \rightarrow B} = -kx \hat{i} \quad \text{Force on block}$$

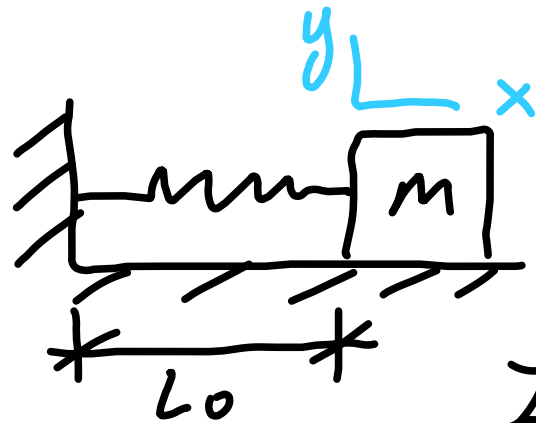
$$\text{so } \vec{F}_{B \rightarrow S} = +kx \hat{i} \quad \text{Force on spring}$$

Look at block



$$W_B = -\int kx dx = -\frac{1}{2}kx^2$$

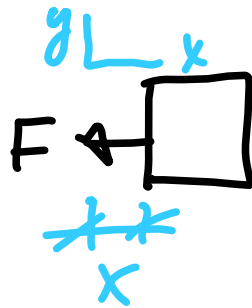
We are going to look a bit closer at a spring system



$$\vec{F}_{S \rightarrow B} = -kx \hat{i} \quad \text{Force on block}$$

$$\text{so } \vec{F}_{B \rightarrow S} = +kx \hat{i} \quad \text{Force on spring}$$

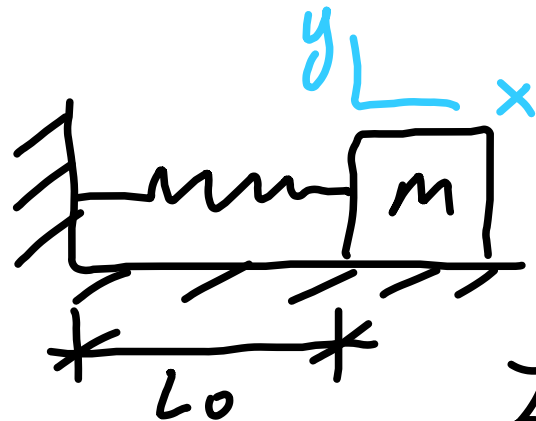
Look at block



$$W_B = -\int kx dx = -\frac{1}{2}kx^2$$

$$\text{so } W_B = K_2 - K_1$$

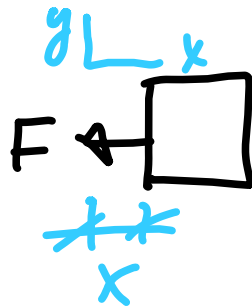
We are going to look a bit closer at a spring system



$$\vec{F}_{S \rightarrow B} = -kx \hat{i} \quad \text{Force on block}$$

$$\text{so } \vec{F}_{B \rightarrow S} = +kx \hat{i} \quad \text{Force on spring}$$

Look at block

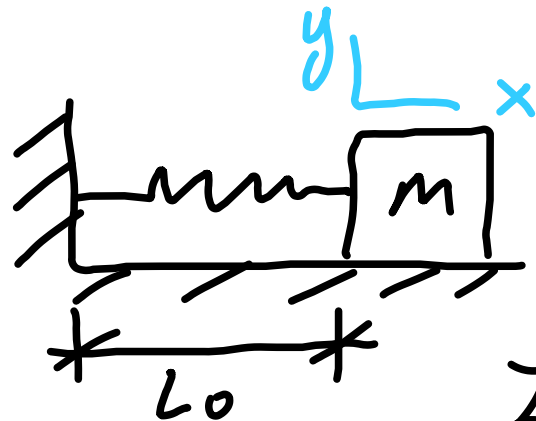


$$w_B = -\int kx dx = -\frac{1}{2}kx^2$$

$$\text{so } w_B = K_2 - K_1$$

$$\text{But } \delta U = -w$$

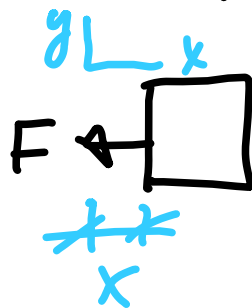
We are going to look a bit closer at a spring system



$$\vec{F}_{S \rightarrow B} = -kx \hat{i} \quad \text{Force on block}$$

$$\text{so } \vec{F}_{B \rightarrow S} = +kx \hat{i} \quad \text{Force on spring}$$

Look at block



$$w_B = -\int kx dx = -\frac{1}{2}kx^2$$

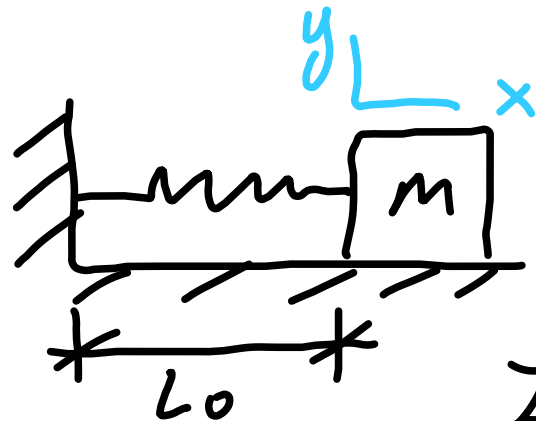
$$\text{so } w_B = k_2 - k_1$$

$$\text{But } \delta U = -W$$

so

$$-(U_2 - U_1) = k_2 - k_1$$

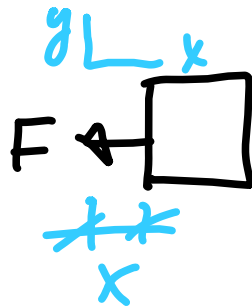
We are going to look a bit closer at a spring system



$$\vec{F}_{S \rightarrow B} = -kx \hat{i} \quad \text{Force on block}$$

$$\text{so } \vec{F}_{B \rightarrow S} = +kx \hat{i} \quad \text{Force on spring}$$

Look at block



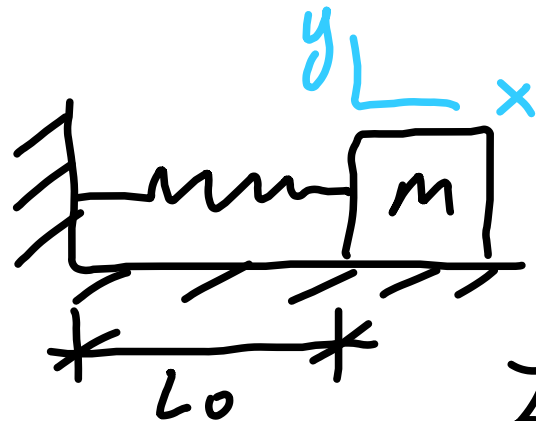
$$w_B = -\int kx dx = -\frac{1}{2}kx^2$$

$$\text{so } w_B = k_2 - k_1$$

$$\text{But } \delta U = -w \quad \text{so} \quad -(U_2 - U_1) = k_2 - k_1$$

$$\Rightarrow U_1 + k_1 = U_2 + k_2$$

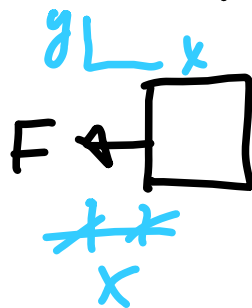
We are going to look a bit closer at a spring system



$$\vec{F}_{S \rightarrow B} = -kx \hat{i} \quad \text{Force on block}$$

$$\text{so } \vec{F}_{B \rightarrow S} = +kx \hat{i} \quad \text{Force on spring}$$

Look at block



$$w_B = -\int kx dx = -\frac{1}{2}kx^2$$

$$\text{so } w_B = k_2 - k_1$$

$$\text{But } \delta U = -w \quad \text{so} \quad -(U_2 - U_1) = k_2 - k_1$$

$$\Rightarrow U_1 + k_1 = U_2 + k_2, \text{ where}$$

$$U = \frac{1}{2}kx^2$$

In our previous analysis  
we saw that the spring was not  
much more than a transmitter of force

In our previous analysis we saw that the spring was not much more than a transmitter of force

The analysis was more meaningful when looking at the force provided by the spring than the other way.

In our previous analysis we saw that the spring was not much more than a transmitter of force

The analysis was more meaningful when looking at the force provided by the spring than the other way.

Typically we can neglect the force on spring

In our previous analysis we saw that the spring was not much more than a transmitter of force

The analysis was more meaningful when looking at the force provided by the spring than the other way.

Typically we can neglect the force on spring & work performed on spring.

In our previous analysis we saw that the spring was not much more than a transmitter of force

The analysis was more meaningful when looking at the force provided by the spring than the other way.

Typically we can neglect the force on spring & work performed on spring. Instead, it is the force by spring

In our previous analysis we saw that the spring was not much more than a transmitter of force

The analysis was more meaningful when looking at the force provided by the spring than the other way.

Typically we can neglect the force on spring & work performed on spring. Instead, it is the force by spring & work performed by spring that are useful

# Four properties of conservative forces

Four properties of conservative forces:

1) Can be expressed as the difference between initial & final values of a potential energy function

## Four properties of conservative forces:

- 1) Can be expressed as the difference between initial & final values of a potential energy function
- 2) Reversible

## Four properties of conservative forces:

- 1) Can be expressed as the difference between initial & final values of a potential energy function
- 2) Reversible
- 3) Path independent & only depends on end points

## Four properties of conservative forces:

1) Can be expressed as the difference between initial & final values of a potential energy function

2) Reversible

3) Path independent & only depends on end points

4) When starting & ending endpoints are the same, total work is zero

You are rearranging your furniture and wish to move a 40.0 kg futon 2.50 m across the room. A heavy coffee table, which you don't want to move, blocks this straight-line path. Instead, you slide the futon along a dogleg path; the doglegs are 2.00 m and 1.50 m long. How much more work must you do to push the futon along the dogleg path than along the straight-line path? The coefficient of kinetic friction is  $\mu_k = 0.200$ .

You are rearranging your furniture and wish to move a 40.0 kg futon 2.50 m across the room. A heavy coffee table, which you don't want to move, blocks this straight-line path. Instead, you slide the futon along a dogleg path; the doglegs are 2.00 m and 1.50 m long. How much more work must you do to push the futon along the dogleg path than along the straight-line path? The coefficient of kinetic friction is  $\mu_k = 0.200$ .

$$m = 40 \text{ kg} , L = 2.5 \text{ m}$$

You are rearranging your furniture and wish to move a 40.0 kg futon 2.50 m across the room. A heavy coffee table, which you don't want to move, blocks this straight-line path. Instead, you slide the futon along a dogleg path; the doglegs are 2.00 m and 1.50 m long. How much more work must you do to push the futon along the dogleg path than along the straight-line path? The coefficient of kinetic friction is  $\mu_k = 0.200$ .

$$m = 40 \text{ kg}, L = 2.5 \text{ m}, L_1 = 2 \text{ m}, L_2 = 1.5 \text{ m}$$

You are rearranging your furniture and wish to move a 40.0 kg futon 2.50 m across the room. A heavy coffee table, which you don't want to move, blocks this straight-line path. Instead, you slide the futon along a dogleg path; the doglegs are 2.00 m and 1.50 m long. How much more work must you do to push the futon along the dogleg path than along the straight-line path? The coefficient of kinetic friction is  $\mu_k = 0.200$ .

$$m = 40 \text{ kg}, L = 2.5 \text{ m}, L_1 = 2 \text{ m}, L_2 = 1.5 \text{ m}, \mu_k = 0.2$$

You are rearranging your furniture and wish to move a 40.0 kg futon 2.50 m across the room. A heavy coffee table, which you don't want to move, blocks this straight-line path. Instead, you slide the futon along a dogleg path; the doglegs are 2.00 m and 1.50 m long. How much more work must you do to push the futon along the dogleg path than along the straight-line path? The coefficient of kinetic friction is  $\mu_k = 0.200$ .

$$m = 40 \text{ kg}, L = 2.5 \text{ m}, L_1 = 2 \text{ m}, L_2 = 1.5 \text{ m}, \mu_k = 0.2$$

You are rearranging your furniture and wish to move a 40.0 kg futon 2.50 m across the room. A heavy coffee table, which you don't want to move, blocks this straight-line path. Instead, you slide the futon along a dogleg path; the doglegs are 2.00 m and 1.50 m long. How much more work must you do to push the futon along the dogleg path than along the straight-line path? The coefficient of kinetic friction is  $\mu_k = 0.200$ .

$$m = 40 \text{ kg}, L = 2.5 \text{ m}, L_1 = 2 \text{ m}, L_2 = 1.5 \text{ m}, \mu_k = 0.2$$

$$F_f = mg\mu_k$$

You are rearranging your furniture and wish to move a 40.0 kg futon 2.50 m across the room. A heavy coffee table, which you don't want to move, blocks this straight-line path. Instead, you slide the futon along a dogleg path; the doglegs are 2.00 m and 1.50 m long. How much more work must you do to push the futon along the dogleg path than along the straight-line path? The coefficient of kinetic friction is  $\mu_k = 0.200$ .

$$m = 40 \text{ kg}, \quad L = 2.5 \text{ m}, \quad L_1 = 2 \text{ m}, \quad L_2 = 1.5 \text{ m}, \quad \mu_k = 0.2$$

$$F_f = mg\mu_k \quad \& \quad W_L = mg\mu_k L \quad \leftarrow \text{work performed against friction}$$

You are rearranging your furniture and wish to move a 40.0 kg futon 2.50 m across the room. A heavy coffee table, which you don't want to move, blocks this straight-line path. Instead, you slide the futon along a dogleg path; the doglegs are 2.00 m and 1.50 m long. How much more work must you do to push the futon along the dogleg path than along the straight-line path? The coefficient of kinetic friction is  $\mu_k = 0.200$ .

$$m = 40 \text{ kg}, L = 2.5 \text{ m}, L_1 = 2 \text{ m}, L_2 = 1.5 \text{ m}, \mu_k = 0.2$$

$$F_f = mg\mu_k \quad \& \quad W_L = mg\mu_k L \quad \&$$

$$W_{L_1} + W_{L_2} = mg\mu_k (L_1 + L_2)$$

You are rearranging your furniture and wish to move a 40.0 kg futon 2.50 m across the room. A heavy coffee table, which you don't want to move, blocks this straight-line path. Instead, you slide the futon along a dogleg path; the doglegs are 2.00 m and 1.50 m long. How much more work must you do to push the futon along the dogleg path than along the straight-line path? The coefficient of kinetic friction is  $\mu_k = 0.200$ .

$$m = 40 \text{ kg}, \quad L = 2.5 \text{ m}, \quad L_1 = 2 \text{ m}, \quad L_2 = 1.5 \text{ m}, \quad \mu_k = 0.2$$

$$F_f = mg\mu_k \quad \& \quad W_L = mg\mu_k L \quad \&$$

$$W_{L_1} + W_{L_2} = mg\mu_k (L_1 + L_2) \quad \text{So}$$

$$[W_{L_1} + W_{L_2}] - W_L = mg\mu_k [L_1 + L_2 - L]$$

You are rearranging your furniture and wish to move a 40.0 kg futon 2.50 m across the room. A heavy coffee table, which you don't want to move, blocks this straight-line path. Instead, you slide the futon along a dogleg path; the doglegs are 2.00 m and 1.50 m long. How much more work must you do to push the futon along the dogleg path than along the straight-line path? The coefficient of kinetic friction is  $\mu_k = 0.200$ .

$$m = 40 \text{ kg}, \quad L = 2.5 \text{ m}, \quad L_1 = 2 \text{ m}, \quad L_2 = 1.5 \text{ m}, \quad \mu_k = 0.2$$

$$F_f = mg\mu_k \quad \& \quad W_L = mg\mu_k L \quad \&$$

$$W_{L_1} + W_{L_2} = mg\mu_k (L_1 + L_2) \quad \text{So}$$

$$\begin{aligned} [W_{L_1} + W_{L_2}] - W_L &= mg\mu_k [L_1 + L_2 - L] \\ &= 40 * 9.8 * 0.2 * [3.5 - 2.5] \text{ J} \end{aligned}$$

You are rearranging your furniture and wish to move a 40.0 kg futon 2.50 m across the room. A heavy coffee table, which you don't want to move, blocks this straight-line path. Instead, you slide the futon along a dogleg path; the doglegs are 2.00 m and 1.50 m long. How much more work must you do to push the futon along the dogleg path than along the straight-line path? The coefficient of kinetic friction is  $\mu_k = 0.200$ .

$$m = 40 \text{ kg}, \quad L = 2.5 \text{ m}, \quad L_1 = 2 \text{ m}, \quad L_2 = 1.5 \text{ m}, \quad \mu_k = 0.2$$

$$F_f = mg\mu_k \quad \& \quad W_L = mg\mu_k L \quad \&$$

$$W_{L_1} + W_{L_2} = mg\mu_k (L_1 + L_2) \quad \text{So}$$

$$\begin{aligned} [W_{L_1} + W_{L_2}] - W_L &= mg\mu_k [L_1 + L_2 - L] \\ &= 40 * 9.8 * 0.2 * [3.5 - 2.5] \text{ J} \\ &= 78.4 \text{ J} \end{aligned}$$

You are rearranging your furniture and wish to move a 40.0 kg futon 2.50 m across the room. A heavy coffee table, which you don't want to move, blocks this straight-line path. Instead, you slide the futon along a dogleg path; the doglegs are 2.00 m and 1.50 m long. How much more work must you do to push the futon along the dogleg path than along the straight-line path? The coefficient of kinetic friction is  $\mu_k = 0.200$ .

$$m = 40 \text{ kg}, \quad L = 2.5 \text{ m}, \quad L_1 = 2 \text{ m}, \quad L_2 = 1.5 \text{ m}, \quad \mu_k = 0.2$$

$$F_f = mg\mu_k \quad \& \quad W_L = mg\mu_k L \quad \&$$

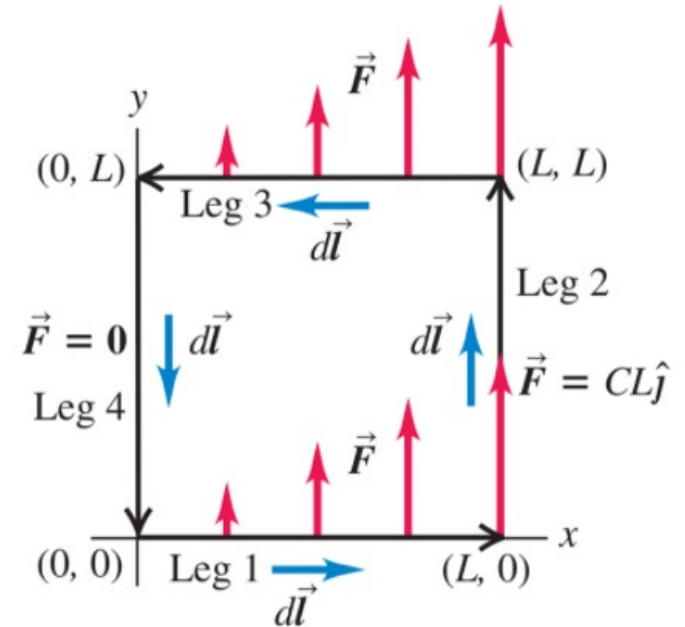
$$W_{L_1} + W_{L_2} = mg\mu_k (L_1 + L_2) \quad \text{So}$$

$$\begin{aligned} [W_{L_1} + W_{L_2}] - W_L &= mg\mu_k [L_1 + L_2 - L] \\ &= 40 * 9.8 * 0.2 * [3.5 - 2.5] \text{ J} \\ &= 78.4 \text{ J} \end{aligned}$$



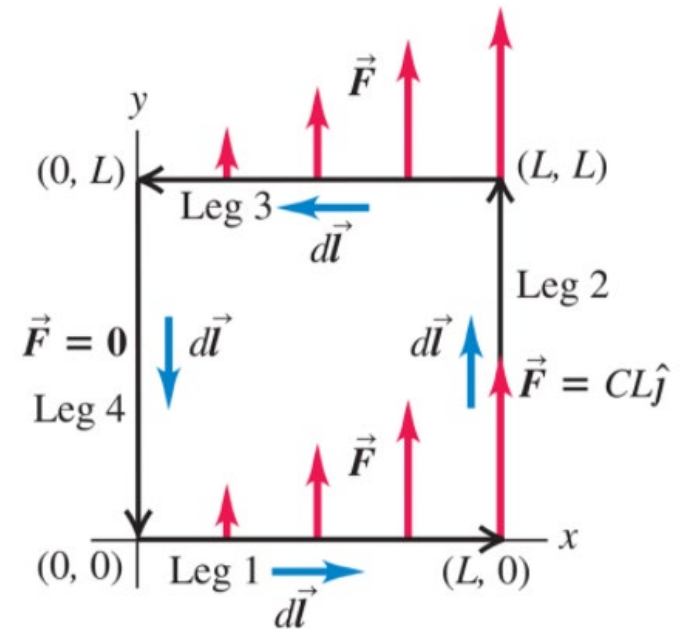
Path dependent  
so nonconservative force

In a region of space the force on an electron is  $\vec{F} = Cx\hat{j}$ , where  $C$  is a positive constant. The electron moves around a square loop in the  $xy$ -plane (Fig. 7.20□). Calculate the work done on the electron by force  $\vec{F}$  during a counterclockwise trip around the square. Is this force conservative or nonconservative?



In a region of space the force on an electron is  $\vec{F} = Cx\hat{j}$ , where  $C$  is a positive constant. The electron moves around a square loop in the  $xy$ -plane (Fig. 7.20□). Calculate the work done on the electron by force  $\vec{F}$  during a counterclockwise trip around the square. Is this force conservative or nonconservative?

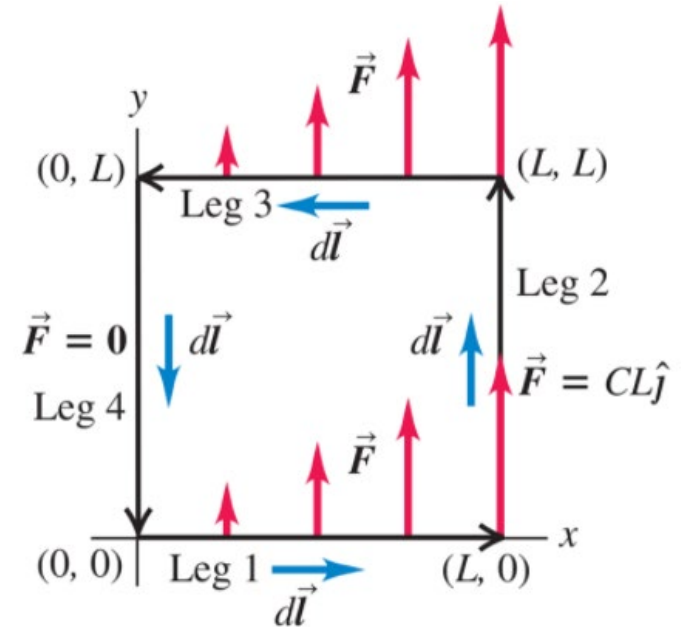
$$\vec{F} = Cx\hat{j}$$



In a region of space the force on an electron is  $\vec{F} = Cx\hat{j}$ , where  $C$  is a positive constant. The electron moves around a square loop in the  $xy$ -plane (Fig. 7.20). Calculate the work done on the electron by force  $\vec{F}$  during a counterclockwise trip around the square. Is this force conservative or nonconservative?

$$\vec{F} = Cx\hat{j}$$

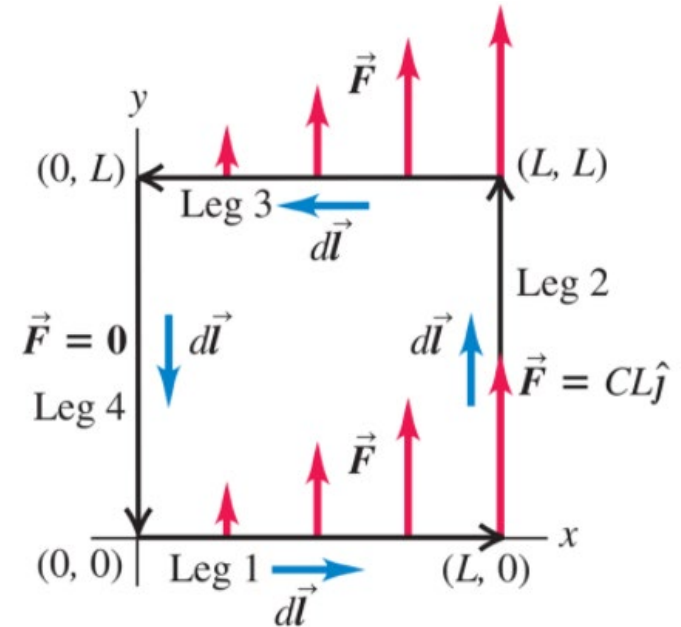
$$W = \int_0^L Cx\hat{j} \cdot d\vec{\ell}_1 +$$



In a region of space the force on an electron is  $\vec{F} = Cx\hat{j}$ , where  $C$  is a positive constant. The electron moves around a square loop in the  $xy$ -plane (Fig. 7.20□). Calculate the work done on the electron by force  $\vec{F}$  during a counterclockwise trip around the square. Is this force conservative or nonconservative?

$$W = \int_0^L Cx\hat{j} \cdot d\vec{\ell}_1 + \int_0^L Cx\hat{j} \cdot d\vec{\ell}_2 +$$

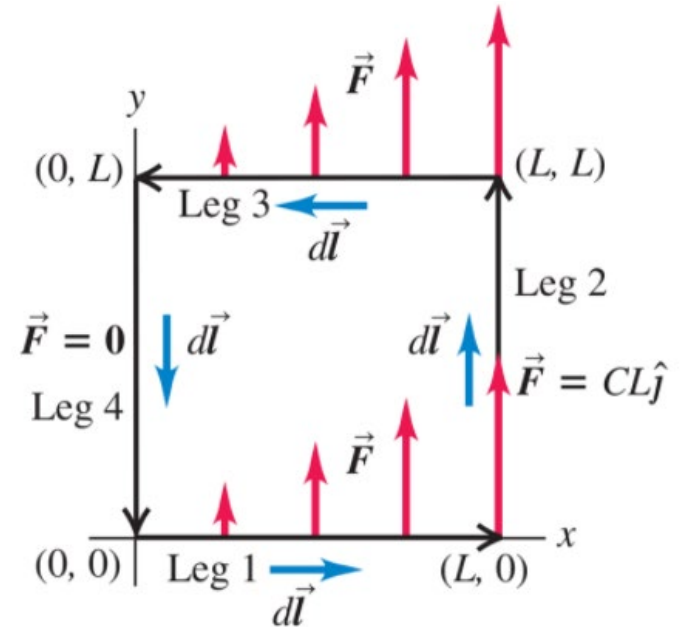
$$\vec{F} = Cx\hat{j}$$



In a region of space the force on an electron is  $\vec{F} = Cx\hat{j}$ , where  $C$  is a positive constant. The electron moves around a square loop in the  $xy$ -plane (Fig. 7.20). Calculate the work done on the electron by force  $\vec{F}$  during a counterclockwise trip around the square. Is this force conservative or nonconservative?

$$\vec{F} = Cx\hat{j}$$

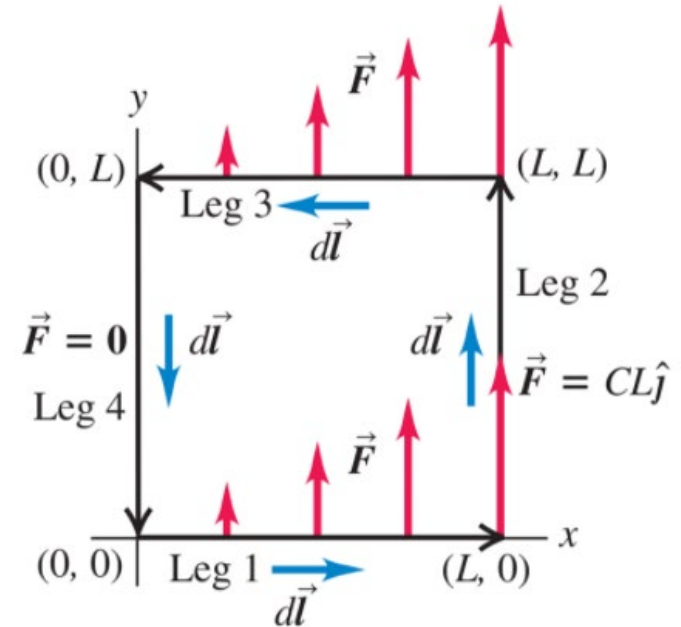
$$W = \int_0^L Cx\hat{j} \cdot d\vec{\ell}_1 + \int_0^L Cx\hat{j} \cdot d\vec{\ell}_2 + \int_L^0 Cx\hat{j} \cdot d\vec{\ell}_3 + \int_0^0 Cx\hat{j} \cdot d\vec{\ell}_4 +$$



In a region of space the force on an electron is  $\vec{F} = Cx\hat{j}$ , where  $C$  is a positive constant. The electron moves around a square loop in the  $xy$ -plane (Fig. 7.20). Calculate the work done on the electron by force  $\vec{F}$  during a counterclockwise trip around the square. Is this force conservative or nonconservative?

$$\vec{F} = Cx\hat{j}$$

$$W = \int_0^L Cx\hat{j} \cdot d\vec{\ell}_1 + \int_0^L Cx\hat{j} \cdot d\vec{\ell}_2 + \int_L^0 Cx\hat{j} \cdot d\vec{\ell}_3 + \int_L^0 Cx\hat{j} \cdot d\vec{\ell}_4$$

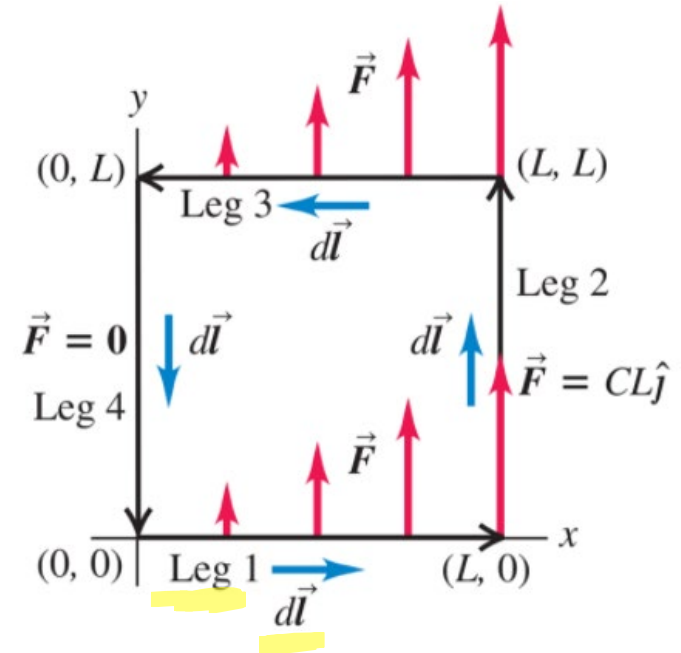


In a region of space the force on an electron is  $\vec{F} = Cx\hat{j}$ , where  $C$  is a positive constant. The electron moves around a square loop in the  $xy$ -plane (Fig. 7.20). Calculate the work done on the electron by force  $\vec{F}$  during a counterclockwise trip around the square. Is this force conservative or nonconservative?

$$\vec{F} = Cx\hat{j}$$

$$W = \int_0^L Cx\hat{j} \cdot d\vec{\ell}_1 + \int_0^L Cx\hat{j} \cdot d\vec{\ell}_2 + \int_L^0 Cx\hat{j} \cdot d\vec{\ell}_3 + \int_L^0 Cx\hat{j} \cdot d\vec{\ell}_4$$

$$\text{But } d\vec{\ell}_1 = \hat{i} dx$$

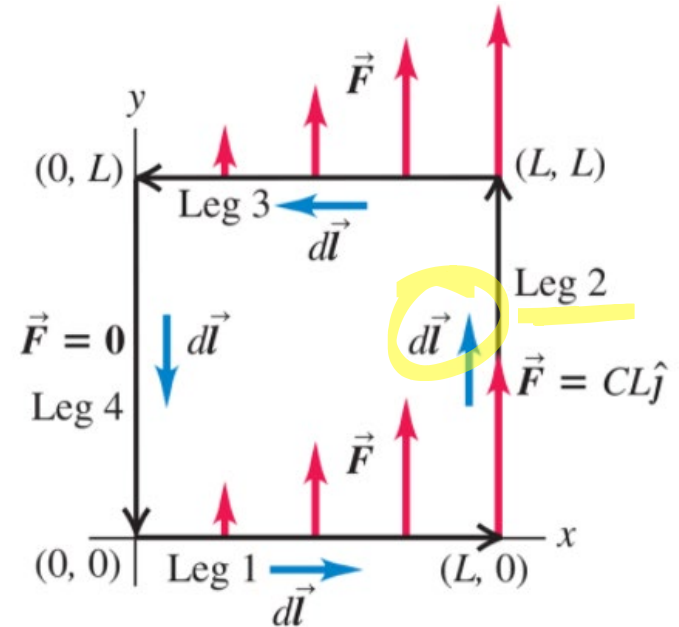


In a region of space the force on an electron is  $\vec{F} = Cx\hat{j}$ , where  $C$  is a positive constant. The electron moves around a square loop in the  $xy$ -plane (Fig. 7.20). Calculate the work done on the electron by force  $\vec{F}$  during a counterclockwise trip around the square. Is this force conservative or nonconservative?

$$\vec{F} = Cx\hat{j}$$

$$W = \int_0^L Cx\hat{j} \cdot d\vec{l}_1 + \int_0^L Cx\hat{j} \cdot d\vec{l}_2 + \int_L^0 Cx\hat{j} \cdot d\vec{l}_3 + \int_L^0 Cx\hat{j} \cdot d\vec{l}_4$$

But  $d\vec{l}_1 = \hat{i} dx$ ,  $d\vec{l}_2 = \hat{j} dy$ ,

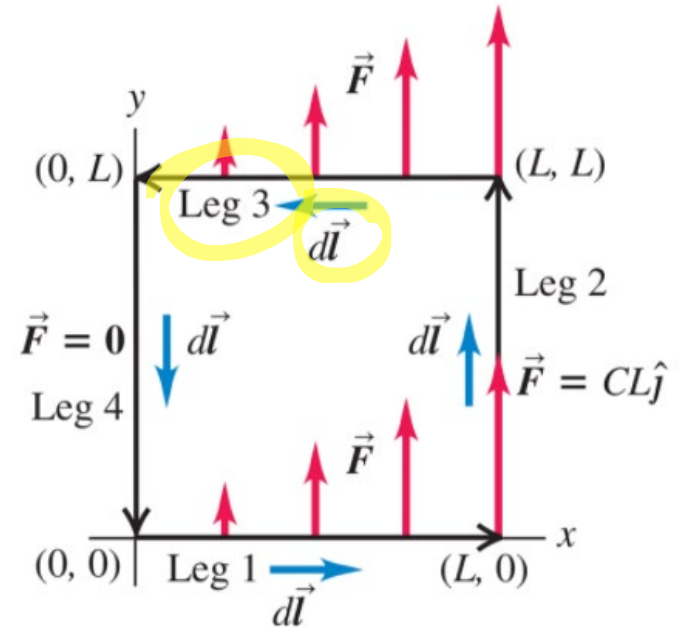


In a region of space the force on an electron is  $\vec{F} = Cx\hat{j}$ , where  $C$  is a positive constant. The electron moves around a square loop in the  $xy$ -plane (Fig. 7.20). Calculate the work done on the electron by force  $\vec{F}$  during a counterclockwise trip around the square. Is this force conservative or nonconservative?

$$\vec{F} = Cx\hat{j}$$

$$W = \int_0^L Cx\hat{j} \cdot d\vec{l}_1 + \int_0^L Cx\hat{j} \cdot d\vec{l}_2 + \int_L^0 Cx\hat{j} \cdot d\vec{l}_3 + \int_L^0 Cx\hat{j} \cdot d\vec{l}_4$$

But  $d\vec{l}_1 = \hat{i} dx$ ,  $d\vec{l}_2 = \hat{j} dy$ ,  
 $d\vec{l}_3 = \hat{i} dx$

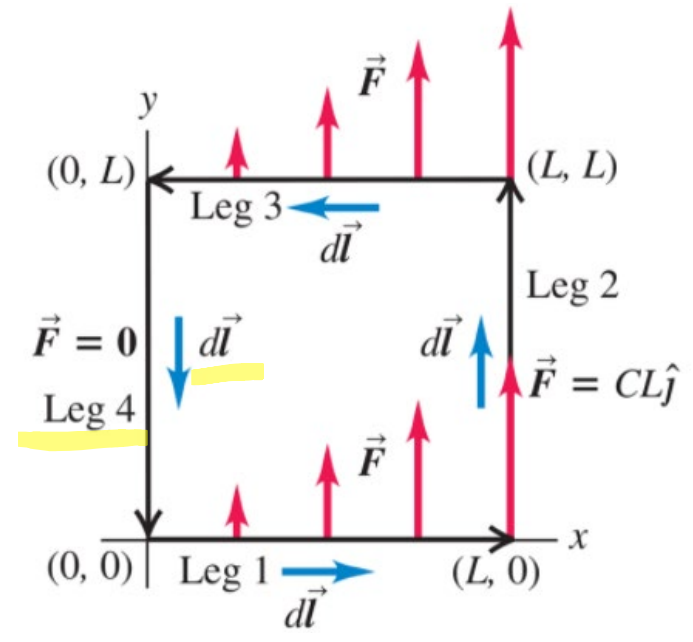


In a region of space the force on an electron is  $\vec{F} = Cx\hat{j}$ , where  $C$  is a positive constant. The electron moves around a square loop in the  $xy$ -plane (Fig. 7.20). Calculate the work done on the electron by force  $\vec{F}$  during a counterclockwise trip around the square. Is this force conservative or nonconservative?

$$\vec{F} = Cx\hat{j}$$

$$W = \int_0^L Cx\hat{j} \cdot d\vec{l}_1 + \int_0^L Cx\hat{j} \cdot d\vec{l}_2 + \int_L^0 Cx\hat{j} \cdot d\vec{l}_3 + \int_L^0 Cx\hat{j} \cdot d\vec{l}_4$$

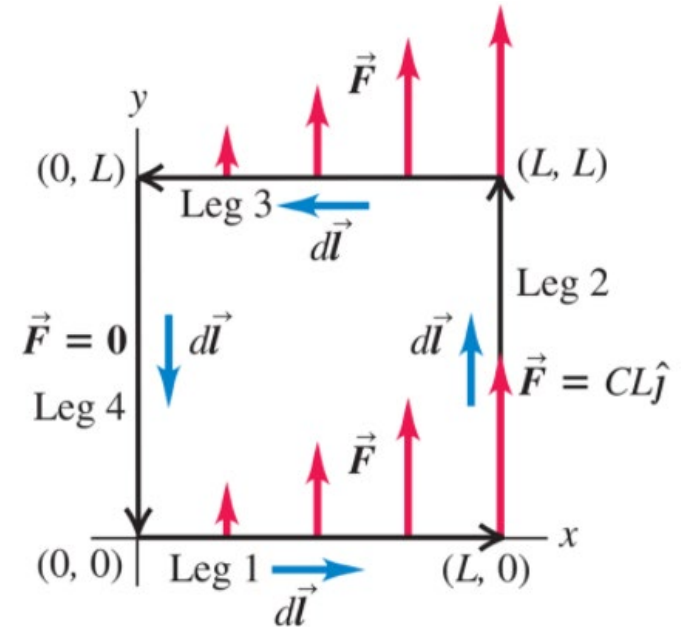
But  $d\vec{l}_1 = \hat{i} dx$ ,  $d\vec{l}_2 = \hat{j} dy$ ,  
 $d\vec{l}_3 = \hat{i} dx$ ,  $d\vec{l}_4 = \hat{j} dy$



In a region of space the force on an electron is  $\vec{F} = Cx\hat{j}$ , where  $C$  is a positive constant. The electron moves around a square loop in the  $xy$ -plane (Fig. 7.20). Calculate the work done on the electron by force  $\vec{F}$  during a counterclockwise trip around the square. Is this force conservative or nonconservative?

$$W = \int_0^L Cx\hat{j} \cdot d\vec{l}_1 + \int_0^L Cx\hat{j} \cdot d\vec{l}_2 + \int_L^0 Cx\hat{j} \cdot d\vec{l}_3 + \int_L^0 Cx\hat{j} \cdot d\vec{l}_4$$

But  $d\vec{l}_1 = \hat{i} dx$ ,  $d\vec{l}_2 = \hat{j} dy$ ,  
 $d\vec{l}_3 = \hat{i} dx$ ,  $d\vec{l}_4 = \hat{j} dy$



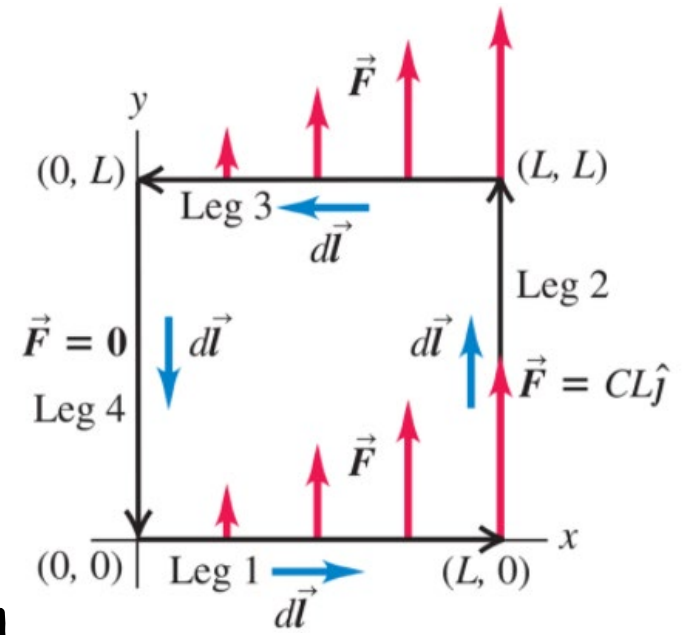
In a region of space the force on an electron is  $\vec{F} = Cx\hat{j}$ , where  $C$  is a positive constant. The electron moves around a square loop in the  $xy$ -plane (Fig. 7.20). Calculate the work done on the electron by force  $\vec{F}$  during a counterclockwise trip around the square. Is this force conservative or nonconservative?

$$\vec{F} = Cx\hat{j}$$

$$W = \int_0^L Cx\hat{j} \cdot d\vec{l}_1 + \int_0^L Cx\hat{j} \cdot d\vec{l}_2 + \int_L^0 Cx\hat{j} \cdot d\vec{l}_3 + \int_L^0 Cx\hat{j} \cdot d\vec{l}_4$$

But  $d\vec{l}_1 = \hat{i} dx$ ,  $d\vec{l}_2 = \hat{j} dy$ ,  
 $d\vec{l}_3 = \hat{i} dx$ ,  $d\vec{l}_4 = \hat{j} dy$  so

$$W = \int_0^L CL dy +$$



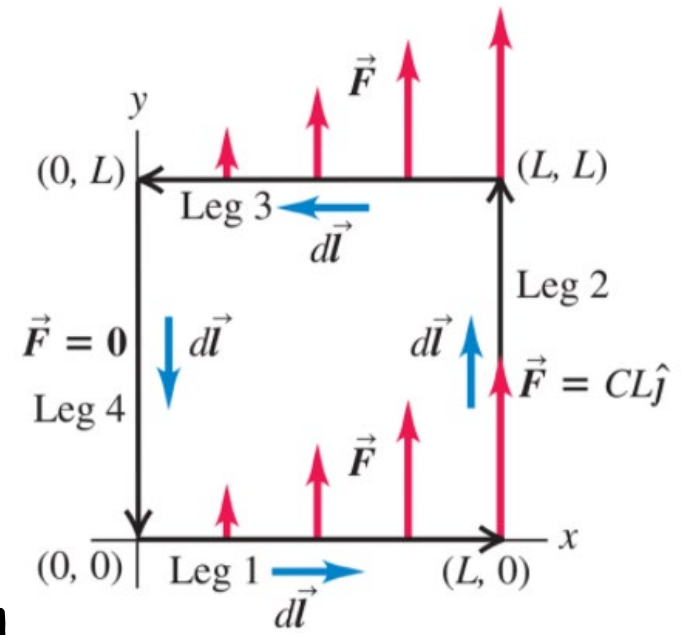
In a region of space the force on an electron is  $\vec{F} = Cx\hat{j}$ , where  $C$  is a positive constant. The electron moves around a square loop in the  $xy$ -plane (Fig. 7.20). Calculate the work done on the electron by force  $\vec{F}$  during a counterclockwise trip around the square. Is this force conservative or nonconservative?

$$\vec{F} = Cx\hat{j}$$

$$W = \int_0^L Cx\hat{j} \cdot d\vec{l}_1 + \int_0^L Cx\hat{j} \cdot d\vec{l}_2 + \int_L^0 Cx\hat{j} \cdot d\vec{l}_3 + \int_L^0 Cx\hat{j} \cdot d\vec{l}_4$$

But  $d\vec{l}_1 = \hat{i} dx$ ,  $d\vec{l}_2 = \hat{j} dy$ ,  
 $d\vec{l}_3 = \hat{i} dx$ ,  $d\vec{l}_4 = \hat{j} dy$  *no*

$$W = \int_0^L CL dy + \int_L^0 C \cdot 0 dy \quad \text{since } F(x=0) = C \cdot 0$$



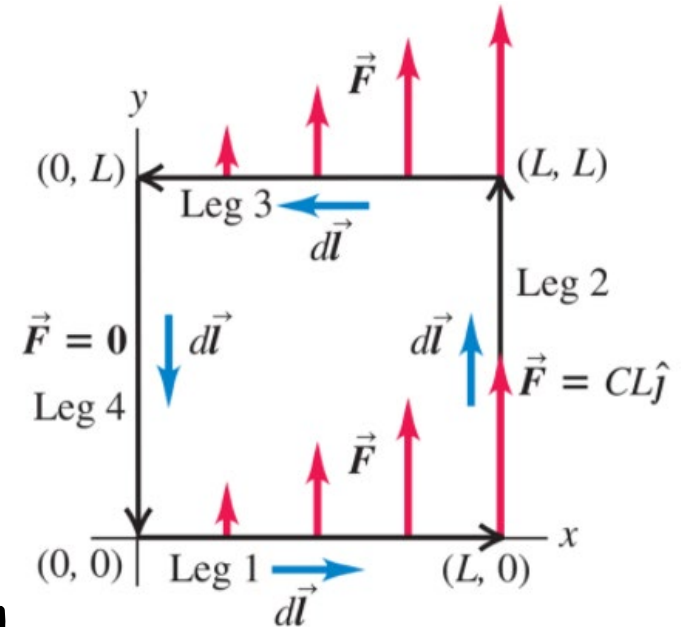
In a region of space the force on an electron is  $\vec{F} = Cx\hat{j}$ , where  $C$  is a positive constant. The electron moves around a square loop in the  $xy$ -plane (Fig. 7.20). Calculate the work done on the electron by force  $\vec{F}$  during a counterclockwise trip around the square. Is this force conservative or nonconservative?

$$W = \int_0^L Cx\hat{j} \cdot d\vec{l}_1 + \int_0^L Cx\hat{j} \cdot d\vec{l}_2 + \int_L^0 Cx\hat{j} \cdot d\vec{l}_3 + \int_L^0 Cx\hat{j} \cdot d\vec{l}_4$$

But  $d\vec{l}_1 = \hat{i} dx$ ,  $d\vec{l}_2 = \hat{j} dy$ ,  
 $d\vec{l}_3 = \hat{i} dx$ ,  $d\vec{l}_4 = \hat{j} dy$  so

$$W = \int_0^L CL dy + \int_L^0 C \cdot 0 dy$$

so  $W = CL^2$



In a region of space the force on an electron is  $\vec{F} = Cx\hat{j}$ , where  $C$  is a positive constant. The electron moves around a square loop in the  $xy$ -plane (Fig. 7.20). Calculate the work done on the electron by force  $\vec{F}$  during a counterclockwise trip around the square. Is this force conservative or nonconservative?

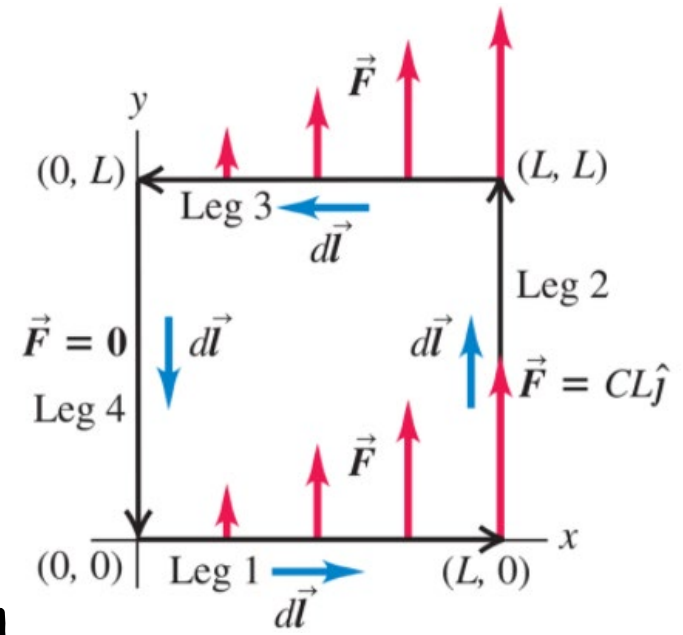
$$\vec{F} = Cx\hat{j}$$

$$W = \int_0^L Cx\hat{j} \cdot d\vec{l}_1 + \int_0^L Cx\hat{j} \cdot d\vec{l}_2 + \int_L^0 Cx\hat{j} \cdot d\vec{l}_3 + \int_L^0 Cx\hat{j} \cdot d\vec{l}_4$$

But  $d\vec{l}_1 = \hat{i} dx$ ,  $d\vec{l}_2 = \hat{j} dy$ ,  
 $d\vec{l}_3 = \hat{i} dx$ ,  $d\vec{l}_4 = \hat{j} dy$  So

$$W = \int_0^L CL dy + \int_L^0 Cx dy$$

So  $W = CL^2$



NONCONSERVATIVE  
 since work for  
 round trip  $\neq 0$



# Internal energy



# Internal energy



While driving, a tire will deform & flex

# Internal energy



While driving, a tire will deform & flex  $\Rightarrow$  heat generation & raised temperature

# Internal energy



While driving, a tire will deform & flex  $\Rightarrow$  heat generation & raised temperature  $\Rightarrow$  Increased internal energy<sup>68</sup>

# Internal energy

# Internal energy

$$\Delta U_{int} = -W_{other}$$

# Internal energy

$$\Delta U_{\text{int}} = -W_{\text{other}}$$

$$\text{So } K_1 + U_1 - \Delta U_{\text{int}} = K_2 + U_2$$

# Internal energy

$$\Delta U_{\text{int}} = -W_{\text{other}}$$

$$\text{So } K_1 + U_1 - \Delta U_{\text{int}} = K_2 + U_2$$

$$\text{or } \Delta K + \Delta U + \Delta U_{\text{int}} = \cancel{0}$$

# Force & potential energy

# Force & potential energy

$$W = -\Delta U$$

# Force & potential energy

$$W = -\Delta U \quad \text{In 1d (say x-direction)}$$

$$W = F_x \Delta x$$

# Force & potential energy

$$W = -\Delta U \quad \text{In 1d (say x-direction)}$$

$$W = F_x \Delta x \Rightarrow F_x \Delta x = -\Delta U$$

## Force & potential energy

$W = -\Delta U$  In 1d (say x-direction)

$$W = F_x \Delta x \Rightarrow F_x \Delta x = -\Delta U \Rightarrow F_x = -\frac{\Delta U}{\Delta x}$$

# Force & potential energy

$$W = -\Delta U \quad \text{In 1d (say x-direction)}$$

$$W = F_x \Delta x \Rightarrow F_x \Delta x = -\Delta U \Rightarrow F_x = -\frac{\Delta U}{\Delta x}$$

$$\Rightarrow F_x = -\frac{dU}{dx}$$

## Force & potential energy

$$W = -\Delta U \quad \text{In 1d (say x-direction)}$$

$$W = F_x \Delta x \Rightarrow F_x \Delta x = -\Delta U \Rightarrow F_x = -\frac{\Delta U}{\Delta x}$$

$$\Rightarrow F_x = -\frac{dU}{dx}$$

For spring  $U = \frac{1}{2} kx^2$

## Force & potential energy

$$W = -\Delta U \quad \text{In 1d (say x-direction)}$$

$$W = F_x \Delta x \Rightarrow F_x \Delta x = -\Delta U \Rightarrow F_x = -\frac{\Delta U}{\Delta x}$$

$$\Rightarrow F_x = -\frac{dU}{dx}$$

For spring  $U = \frac{1}{2} kx^2$  so

$$F_x = -\frac{d}{dx} \left[ \frac{1}{2} kx^2 \right]$$

## Force & potential energy

$$W = -\Delta U \quad \text{In 1d (say x-direction)}$$

$$W = F_x \Delta x \Rightarrow F_x \Delta x = -\Delta U \Rightarrow F_x = -\frac{\Delta U}{\Delta x}$$

$$\Rightarrow F_x = -\frac{dU}{dx}$$

For spring  $U = \frac{1}{2} kx^2$  so

$$F_x = -\frac{d}{dx} \left[ \frac{1}{2} kx^2 \right] = -kx$$

## Force & potential energy

$W = -\Delta U$  In 1d (say x-direction)

$$W = F_x \Delta x \Rightarrow F_x \Delta x = -\Delta U \Rightarrow F_x = -\frac{\Delta U}{\Delta x}$$

$$\Rightarrow F_x = -\frac{dU}{dx}$$

For spring  $U = \frac{1}{2} kx^2$  so

$$F_x = -\frac{d}{dx} \left[ \frac{1}{2} kx^2 \right] = -kx$$

For gravity  $U = mgy$

## Force & potential energy

$W = -\Delta U$  In 1d (say x-direction)

$$W = F_x \Delta x \Rightarrow F_x \Delta x = -\Delta U \Rightarrow F_x = -\frac{\Delta U}{\Delta x}$$

$$\Rightarrow F_x = -\frac{dU}{dx}$$

For spring  $U = \frac{1}{2} kx^2$  so

$$F_x = -\frac{d}{dx} \left[ \frac{1}{2} kx^2 \right] = -kx$$

For gravity  $U = mgy$  so

$$F_y = -\frac{d}{dy} [mgy]$$

## Force & potential energy

$W = -\Delta U$  In 1d (say x-direction)

$$W = F_x \Delta x \Rightarrow F_x \Delta x = -\Delta U \Rightarrow F_x = -\frac{\Delta U}{\Delta x}$$

$$\Rightarrow F_x = -\frac{dU}{dx}$$

For spring  $U = \frac{1}{2} kx^2$  so

$$F_x = -\frac{d}{dx} \left[ \frac{1}{2} kx^2 \right] = -kx$$

For gravity  $U = mgy$  so

$$F_y = -\frac{d}{dy} [mgy] = -mg$$

An electrically charged particle is held at rest at the point  $x = 0$ ; a second particle with equal charge is free to move along the positive  $x$ -axis. The potential energy of the system is  $U(x) = C/x$ , where  $C$  is a positive constant that depends on the magnitude of the charges. Derive an expression for the  $x$ -component of force acting on the movable particle as a function of its position.

An electrically charged particle is held at rest at the point  $x = 0$ ; a second particle with equal charge is free to move along the positive  $x$ -axis. The potential energy of the system is  $U(x) = C/x$ , where  $C$  is a positive constant that depends on the magnitude of the charges.

Derive an expression for the  $x$ -component of force acting on the movable particle as a function of its position.  $U = C/x$

An electrically charged particle is held at rest at the point  $x = 0$ ; a second particle with equal charge is free to move along the positive  $x$ -axis. The potential energy of the system is  $U(x) = C/x$ , where  $C$  is a positive constant that depends on the magnitude of the charges.

Derive an expression for the  $x$ -component of force acting on the movable particle as a function of its position.

$$U = C/x$$

An electrically charged particle is held at rest at the point  $x = 0$ ; a second particle with equal charge is free to move along the positive  $x$ -axis. The potential energy of the system is  $U(x) = C/x$ , where  $C$  is a positive constant that depends on the magnitude of the charges.

Derive an expression for the  $x$ -component of force acting on the movable particle as a function of its position.

$$u = C/x$$

$$F_x = -\frac{du}{dx}$$

An electrically charged particle is held at rest at the point  $x = 0$ ; a second particle with equal charge is free to move along the positive  $x$ -axis. The potential energy of the system is  $U(x) = C/x$ , where  $C$  is a positive constant that depends on the magnitude of the charges.

Derive an expression for the  $x$ -component of force acting on the movable particle as a function of its position.  $u = C/x$

$$F_x = -\frac{du}{dx} = -\frac{d}{dx}\left[\frac{C}{x}\right]$$

An electrically charged particle is held at rest at the point  $x = 0$ ; a second particle with equal charge is free to move along the positive  $x$ -axis. The potential energy of the system is  $U(x) = C/x$ , where  $C$  is a positive constant that depends on the magnitude of the charges.

Derive an expression for the  $x$ -component of force acting on the movable particle as a function of its position.  $u = C/x$

$$F_x = -\frac{du}{dx} = -\frac{d}{dx}\left[\frac{C}{x}\right] = +\frac{C}{x^2}$$

# 3-d case

3-d case

$$F_x = -\frac{\partial U}{\partial x} ,$$

# 3-d case

$$F_x = -\frac{\partial u}{\partial x} \quad , \quad F_y = -\frac{\partial u}{\partial y}$$

# 3-d case

$$F_x = -\frac{\partial u}{\partial x}, \quad F_y = -\frac{\partial u}{\partial y}, \quad F_z = -\frac{\partial u}{\partial z}$$

# 3-d case

$$F_x = -\frac{\partial u}{\partial x}, \quad F_y = -\frac{\partial u}{\partial y}, \quad F_z = -\frac{\partial u}{\partial z}$$

$$\Rightarrow \vec{F} = -\left(\frac{\partial u}{\partial x} \hat{i} + \frac{\partial u}{\partial y} \hat{j} + \frac{\partial u}{\partial z} \hat{k}\right)$$

# 3-d case

$$F_x = -\frac{\partial u}{\partial x}, \quad F_y = -\frac{\partial u}{\partial y}, \quad F_z = -\frac{\partial u}{\partial z}$$

$$\Rightarrow \vec{F} = -\left(\frac{\partial u}{\partial x} \hat{i} + \frac{\partial u}{\partial y} \hat{j} + \frac{\partial u}{\partial z} \hat{k}\right) = -\vec{\nabla} u$$

# 3-d case

$$F_x = -\frac{\partial u}{\partial x}, \quad F_y = -\frac{\partial u}{\partial y}, \quad F_z = -\frac{\partial u}{\partial z}$$

$$\Rightarrow \vec{F} = -\left(\frac{\partial u}{\partial x} \hat{i} + \frac{\partial u}{\partial y} \hat{j} + \frac{\partial u}{\partial z} \hat{k}\right) = -\vec{\nabla} u$$

Gravity

# 3-d case

$$F_x = -\frac{\partial U}{\partial x}, \quad F_y = -\frac{\partial U}{\partial y}, \quad F_z = -\frac{\partial U}{\partial z}$$

$$\Rightarrow \vec{F} = -\left(\frac{\partial U}{\partial x} \hat{i} + \frac{\partial U}{\partial y} \hat{j} + \frac{\partial U}{\partial z} \hat{k}\right) = -\vec{\nabla} U$$

Gravity  $U = mgy$

# 3-d case

$$F_x = -\frac{\partial U}{\partial x}, \quad F_y = -\frac{\partial U}{\partial y}, \quad F_z = -\frac{\partial U}{\partial z}$$

$$\Rightarrow \vec{F} = -\left(\frac{\partial U}{\partial x} \hat{i} + \frac{\partial U}{\partial y} \hat{j} + \frac{\partial U}{\partial z} \hat{k}\right) = -\vec{\nabla} U$$

---

Gravity  $U = mgy$ ,  $\vec{F} = -\vec{\nabla} U$

# 3-d case

$$F_x = -\frac{\partial U}{\partial x}, \quad F_y = -\frac{\partial U}{\partial y}, \quad F_z = -\frac{\partial U}{\partial z}$$

$$\Rightarrow \vec{F} = -\left(\frac{\partial U}{\partial x} \hat{i} + \frac{\partial U}{\partial y} \hat{j} + \frac{\partial U}{\partial z} \hat{k}\right) = -\vec{\nabla} U$$

Gravity  $U = mgy$ ,  $\vec{F} = -\vec{\nabla} U$

$$\Rightarrow \vec{F} = -\left(\frac{\partial}{\partial x} mgy \hat{i} + \frac{\partial}{\partial y} mgy \hat{j} + \frac{\partial}{\partial z} mgy \hat{k}\right)$$

# 3-d case

$$F_x = -\frac{\partial U}{\partial x}, \quad F_y = -\frac{\partial U}{\partial y}, \quad F_z = -\frac{\partial U}{\partial z}$$

$$\Rightarrow \vec{F} = -\left(\frac{\partial U}{\partial x} \hat{i} + \frac{\partial U}{\partial y} \hat{j} + \frac{\partial U}{\partial z} \hat{k}\right) = -\vec{\nabla} U$$

Gravity  $U = mgy$ ,  $\vec{F} = -\vec{\nabla} U$

$$\Rightarrow \vec{F} = -\left(\cancel{\frac{\partial}{\partial x} mgy} \hat{i} + \frac{\partial}{\partial y} mgy \hat{j} + \cancel{\frac{\partial}{\partial z} mgy} \hat{k}\right)$$

# 3-d case

$$F_x = -\frac{\partial U}{\partial x}, \quad F_y = -\frac{\partial U}{\partial y}, \quad F_z = -\frac{\partial U}{\partial z}$$

$$\Rightarrow \vec{F} = -\left(\frac{\partial U}{\partial x} \hat{i} + \frac{\partial U}{\partial y} \hat{j} + \frac{\partial U}{\partial z} \hat{k}\right) = -\vec{\nabla} U$$

Gravity  $U = mgy$ ,  $\vec{F} = -\vec{\nabla} U$

$$\Rightarrow \vec{F} = -\left(\cancel{\frac{\partial}{\partial x} mgy} \hat{i} + \frac{\partial}{\partial y} mgy \hat{j} + \cancel{\frac{\partial}{\partial z} mgy} \hat{k}\right)$$

$$\Rightarrow \vec{F} = -mgy \hat{j}$$

A puck with coordinates  $x$  and  $y$  slides on a level, frictionless air-hockey table. It is acted on by a conservative force described by the potential-energy function

$$U(x, y) = \frac{1}{2} k (x^2 + y^2)$$

Note that  $r = \sqrt{x^2 + y^2}$  is the distance on the table surface from the puck to the origin. Find a vector expression for the force acting on the puck, and find an expression for the magnitude of the force.



A puck with coordinates  $x$  and  $y$  slides on a level, frictionless air-hockey table. It is acted on by a conservative force described by the potential-energy function

$$U(x, y) = \frac{1}{2} k (x^2 + y^2)$$

Note that  $r = \sqrt{x^2 + y^2}$  is the distance on the table surface from the puck to the origin. Find a vector expression for the force acting on the puck, and find an expression for the magnitude of the force.

$$\frac{\partial U}{\partial x} = kx$$

A puck with coordinates  $x$  and  $y$  slides on a level, frictionless air-hockey table. It is acted on by a conservative force described by the potential-energy function

$$U(x, y) = \frac{1}{2} k (x^2 + y^2)$$

Note that  $r = \sqrt{x^2 + y^2}$  is the distance on the table surface from the puck to the origin. Find a vector expression for the force acting on the puck, and find an expression for the magnitude of the force.

$$\frac{\partial U}{\partial x} = kx \quad \& \quad \frac{\partial U}{\partial y} = ky$$

A puck with coordinates  $x$  and  $y$  slides on a level, frictionless air-hockey table. It is acted on by a conservative force described by the potential-energy function

$$U(x, y) = \frac{1}{2} k (x^2 + y^2)$$

Note that  $r = \sqrt{x^2 + y^2}$  is the distance on the table surface from the puck to the origin. Find a vector expression for the force acting on the puck, and find an expression for the magnitude of the force.

$$\frac{\partial U}{\partial x} = kx \quad \& \quad \frac{\partial U}{\partial y} = ky \quad \Rightarrow$$

$$\vec{F} = -\vec{\nabla}U = -k(\hat{i}x + \hat{j}y)$$

A puck with coordinates  $x$  and  $y$  slides on a level, frictionless air-hockey table. It is acted on by a conservative force described by the potential-energy function

$$U(x, y) = \frac{1}{2} k (x^2 + y^2)$$

Note that  $r = \sqrt{x^2 + y^2}$  is the distance on the table surface from the puck to the origin. Find a vector expression for the force acting on the puck, and find an expression for the magnitude of the force.

$$\frac{\partial U}{\partial x} = kx \quad \& \quad \frac{\partial U}{\partial y} = ky \quad \Rightarrow$$

$$\vec{F} = -\vec{\nabla}U = -k(\hat{i}x + \hat{j}y) \quad \&$$

$$|\vec{F}| = k\sqrt{x^2 + y^2}$$

A puck with coordinates  $x$  and  $y$  slides on a level, frictionless air-hockey table. It is acted on by a conservative force described by the potential-energy function

$$U(x, y) = \frac{1}{2} k (x^2 + y^2)$$

Note that  $r = \sqrt{x^2 + y^2}$  is the distance on the table surface from the puck to the origin. Find a vector expression for the force acting on the puck, and find an expression for the magnitude of the force.

$$\frac{\partial U}{\partial x} = kx \quad \& \quad \frac{\partial U}{\partial y} = ky \quad \Rightarrow$$

$$\vec{F} = -\vec{\nabla}U = -k(\hat{i}x + \hat{j}y) \quad \&$$

$$|\vec{F}| = k\sqrt{x^2 + y^2} = kr$$



A puck with coordinates  $x$  and  $y$  slides on a level, frictionless air-hockey table. It is acted on by a conservative force described by the potential-energy function

$$U(x, y) = \frac{1}{2} k (x^2 + y^2)$$

Note that  $r = \sqrt{x^2 + y^2}$  is the distance on the table surface from the puck to the origin. Find a vector expression for the force acting on the puck, and find an expression for the magnitude of the force.

$$\frac{\partial U}{\partial x} = kx \quad \& \quad \frac{\partial U}{\partial y} = ky \quad \Rightarrow$$

$$\vec{F} = -\vec{\nabla}U = -k(\hat{i}x + \hat{j}y) \quad \&$$

$$|\vec{F}| = k\sqrt{x^2 + y^2} = kr \quad \text{Could have started with } U = \frac{1}{2}kr^2$$



A puck with coordinates  $x$  and  $y$  slides on a level, frictionless air-hockey table. It is acted on by a conservative force described by the potential-energy function

$$U(x, y) = \frac{1}{2} k (x^2 + y^2)$$

Note that  $r = \sqrt{x^2 + y^2}$  is the distance on the table surface from the puck to the origin. Find a vector expression for the force acting on the puck, and find an expression for the magnitude of the force.

$$\frac{\partial U}{\partial x} = kx \quad \& \quad \frac{\partial U}{\partial y} = ky \Rightarrow$$

$$\vec{F} = -\vec{\nabla}U = -k(\hat{i}x + \hat{j}y) \quad \&$$

$$|\vec{F}| = k\sqrt{x^2 + y^2} = kr \quad \text{Could have started with } U = \frac{1}{2}kr^2 \Rightarrow F_r = -\frac{\partial}{\partial r}\left[\frac{1}{2}kr^2\right]$$

A puck with coordinates  $x$  and  $y$  slides on a level, frictionless air-hockey table. It is acted on by a conservative force described by the potential-energy function

$$U(x, y) = \frac{1}{2} k (x^2 + y^2)$$

Note that  $r = \sqrt{x^2 + y^2}$  is the distance on the table surface from the puck to the origin. Find a vector expression for the force acting on the puck, and find an expression for the magnitude of the force.

$$\frac{\partial U}{\partial x} = kx \quad \& \quad \frac{\partial U}{\partial y} = ky \Rightarrow$$

$$\vec{F} = -\vec{\nabla}U = -k(\hat{i}x + \hat{j}y) \quad \&$$

$$|\vec{F}| = k\sqrt{x^2 + y^2} = kr \quad \text{Could have started with } U = \frac{1}{2}kr^2 \Rightarrow F_r = -\frac{\partial}{\partial r}\left[\frac{1}{2}kr^2\right]$$

$$\Rightarrow F_r = -kr$$





